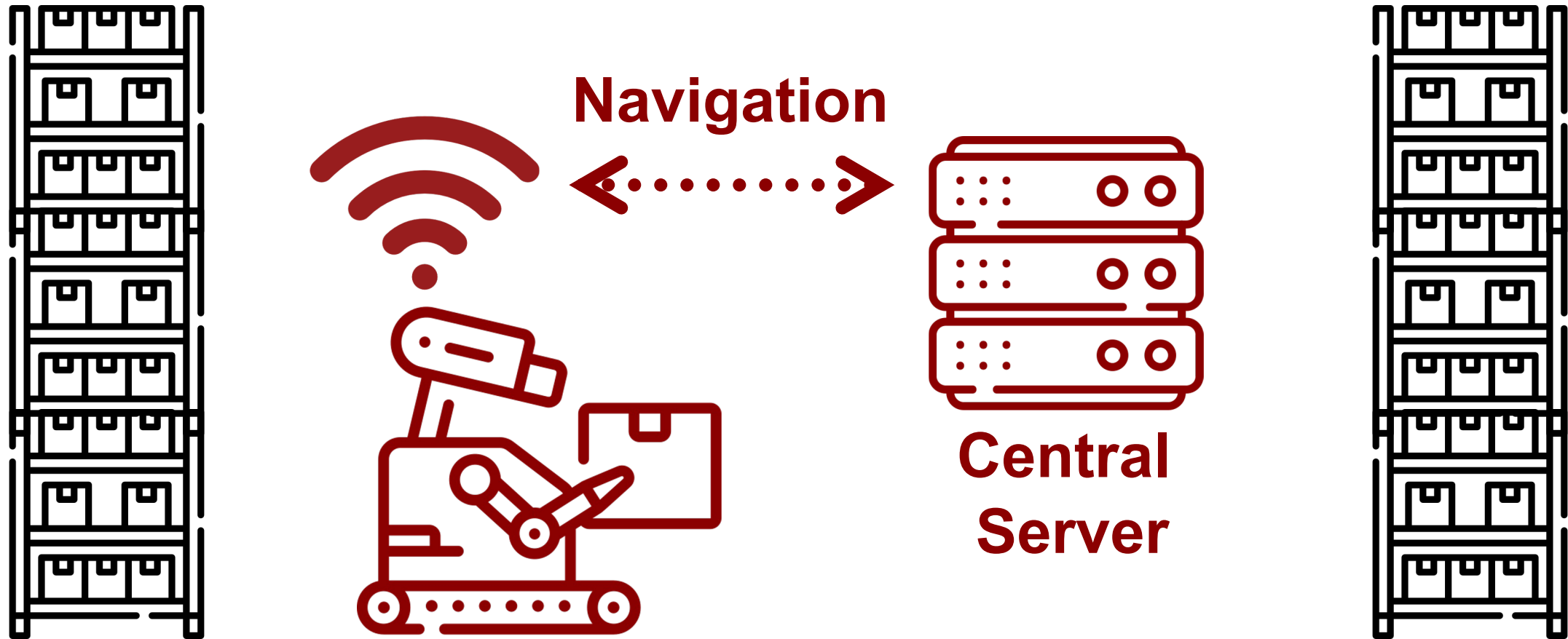


# 17-723: Designing Large-scale Software Systems

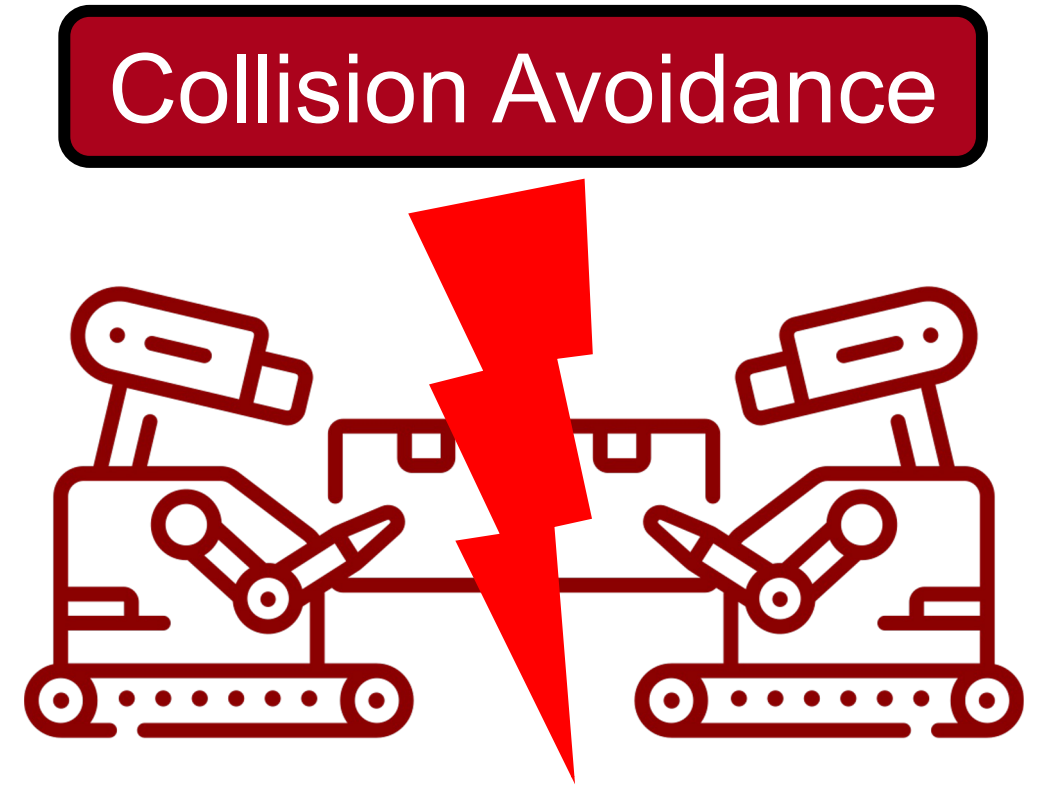
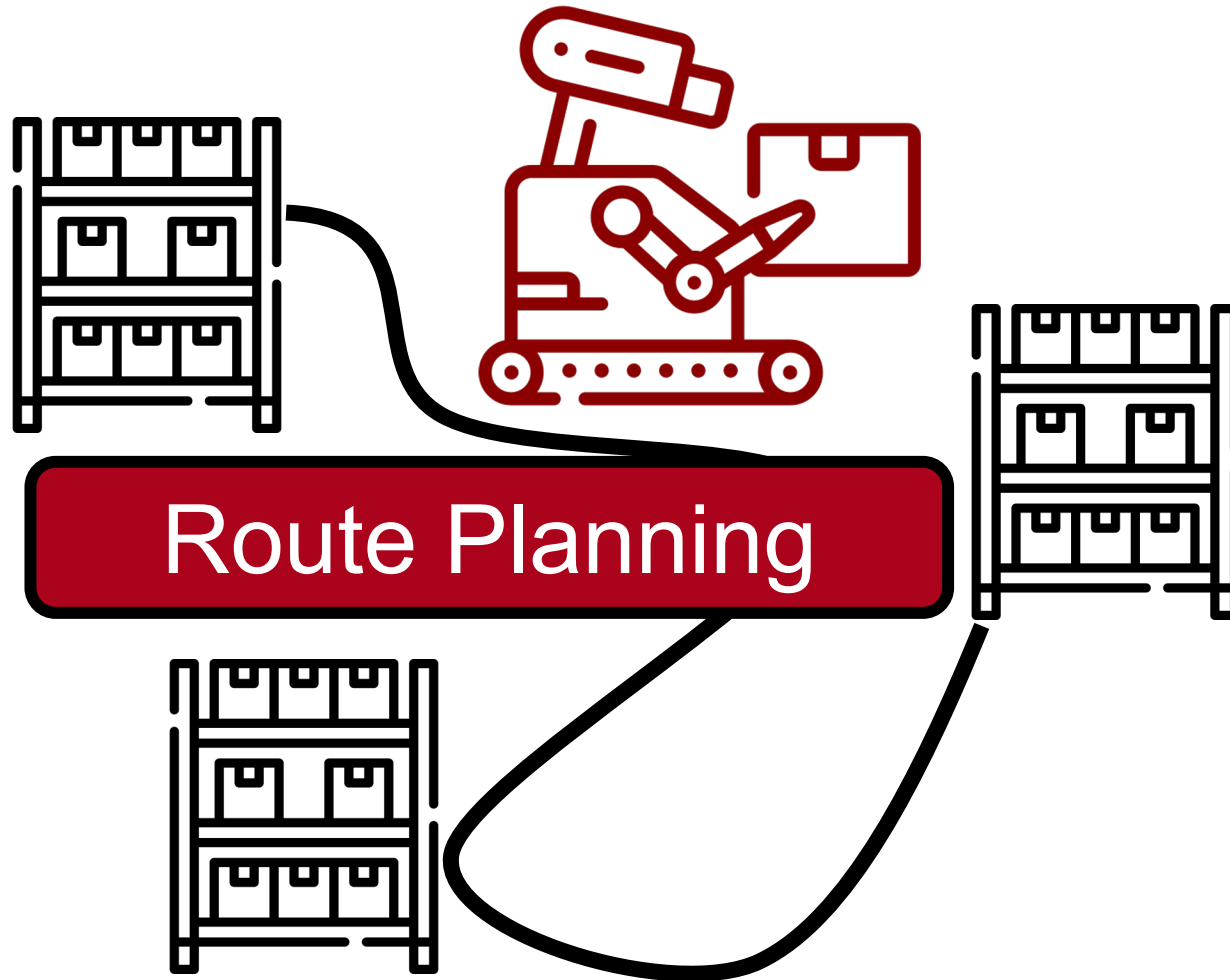
Recitation on Design Tradeoffs

Tobias Dürschmid

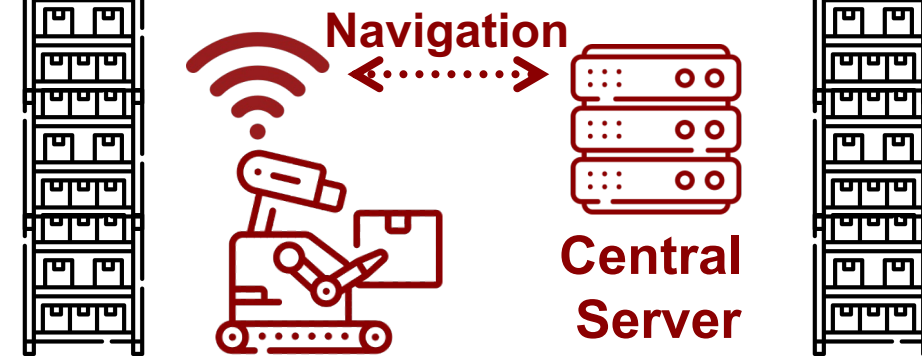
# Design A Server-Supported **Robot Warehouse Navigation System**



# Design a Robot-Server Communication System that supports **Collision Avoidance** and **Route Planning**



# What **Requirements** are Important?



## **Robustness**

The robot should **be able to operate safely** even if the **network is unavailable**.

## **Changeability**

**Updating robot software** should be possible without a robot hardware connection.

## **Scalability**

**Adding new robots** to the system should not degrade individual robot performance.

## **Cost**

The **hardware** and **operating** cost of robots, network, and server should be minimal.

## **Implementation Effort**

The effort to implement **robot** and **server software** should be minimal.

# Shuffle the Groups to Review your Designs

